

NAME:

MATH 672: Vector spaces

Fall'13

Second midterm exam Part 2/2

Partial solutions

1. (20 points) Define:

- (a) Linear functional on a vector space \mathcal{V} .
It is a linear map from \mathcal{V} to its underlying field \mathbb{F} .
- (b) The dual space of a vector space \mathcal{V} .
It is the set of all linear functionals on \mathcal{V} , endowed with addition of operators and multiplication of operators by scalars/
- (c) Alternating k -linear form in a vector space \mathcal{V} .
It is a map of k variables, $\Psi : \mathcal{V} \times \dots \times \mathcal{V} \rightarrow \mathbb{F}$, which is linear in each variable and such that

$$\Psi(v_{\sigma_1}, \dots, v_{\sigma_k}) = \text{sgn}(\sigma)\Psi(v_1, \dots, v_k)$$

for all $\sigma \in S_k$ and $v_1, \dots, v_k \in \mathcal{V}$.

- (d) The transpose/adjoint of an operator $T \in \mathcal{L}(\mathcal{V}, \mathcal{W})$.
It is the operator $T^* : \mathcal{W}^* \rightarrow \mathcal{V}^*$ given by the relation

$$(Tv, w^*) = (v, T^*w^*) \quad \forall v \in \mathcal{V}, \quad w^* \in \mathcal{W}^*,$$

or equivalently $T^*w^* = w^*T$.

2. (15 points) State (giving all hypotheses):

- (a) Cayley-Hamilton's Theorem.
If T is a linear operator in a finite dimensional space and χ_T is its characteristic polynomial, then $\chi_T(T) = 0$.
- (b) The relation between the nullity and the rank of an operator $\mathcal{L}(\mathcal{V}, \mathcal{W})$, where \mathcal{V} and \mathcal{W} are finite dimensional.
 $\rho(T) + \nu(T) = \dim \mathcal{V}$.
- (c) The result that relates the dimensions of the intersection and the sum of two subspaces of a finite dimensional space.
 $\dim \mathcal{V}_1 \cap \mathcal{V}_2 + \dim \mathcal{V}_1 + \mathcal{V}_2 = \dim \mathcal{V}_1 + \dim \mathcal{V}_2$.

3. (25 points) Let T be given by the following relations

$$Tv_1 = 2v_1, \quad Tv_2 = 2v_2 + v_1, \quad Tv_3 = -v_3, \quad Tv_4 = -v_4 + v_3, \quad Tv_5 = 2v_5,$$

where $\{v_1, \dots, v_5\}$ is a basis for \mathcal{V} .

- (a) Find a basis for \mathcal{V} such that the associated matrix is

$$A = \begin{bmatrix} 2 & & & & \\ & 2 & & & \\ & 1 & 2 & & \\ & & & -1 & \\ & & & 1 & -1 \end{bmatrix}$$

(The numbers that are not displayed are zero.)

Let $\mathbf{w} = \{v_5, v_2, v_1, v_4, v_3\}$. It is simple to check that the matrix w.r.t. to \mathbf{w} is A .

- (b) Find all eigenvectors of A . Relate them to eigenvectors of T . (Recall that eigenvectors are organized in subspaces, so eigenvectors should be returned as spans.)

Note that $\chi_T(\lambda) = \chi_A(\lambda) = (2 - \lambda)^3(-1 - \lambda)^2$. Note also that

$$A - 2I = \begin{bmatrix} 0 & & & & \\ & 0 & & & \\ & 1 & 0 & & \\ & & & -3 & \\ & & & 1 & -3 \end{bmatrix} \quad A + I = \begin{bmatrix} 3 & & & & \\ & 3 & & & \\ & 1 & 3 & & \\ & & & 0 & \\ & & & 1 & 0 \end{bmatrix}$$

If $\{e_1, \dots, e_5\}$ are the canonical vectors of \mathbb{F}^5 , then it is a simple observation to note that

$$\ker(A - 2I) = \text{span}[e_1, e_3], \quad \ker(A + I) = \text{span}[e_5].$$

Therefore, relating coordinates in \mathbb{F}^5 to vectors of \mathcal{V} represented in the basis of (a),

$$\ker(T - 2I) = \text{span}[v_5, v_1], \quad \ker(T + I) = \text{span}[v_3].$$

Note that these vectors could already be observed in the original hypotheses of the problem, but we had to show that these were all the eigenvectors.

- (c) Find the minimal polynomial for v_2 and v_5 .

Since $Tv_5 = 2v_5$, then $\min_{P_{T,v_5}}(\lambda) = \lambda - 2$. From the hypotheses it follows that

$$(T - 2I)v_2 = v_1, \quad (T - 2I)^2v_2 = (T - 2I)v_1 = 0,$$

so $\min_{P_{T,v_2}}(\lambda) = (\lambda - 2)^2$.

- (d) Give a reasoned guess of what the minimal polynomial of T is.

Apart from three vectors in the basis that are eigenvectors, we have $\min_{P_{T,v_2}}(\lambda) = (\lambda - 2)^2$ and with exactly the same argument $\min_{P_{T,v_4}}(\lambda) = (\lambda + 1)^2$. Taking the l.c.m. of the minimal polynomials for all the vectors in the basis, it follows that $\min_{P_T}(\lambda) = (\lambda - 2)^2(\lambda + 1)^2$.

- (e) Is T diagonalizable? Why/why not?

From (b) it is clear that we cannot find a basis of \mathcal{V} using eigenvectors of T . Therefore T is not diagonalizable.

4. (20 points) Find the subspace $\mathcal{V} \subset \mathbb{R}_3[x]$ such that

$$\mathcal{V}^\perp = \text{span}[\phi_0, \phi_1], \quad (p, \phi_0) = p(0), \quad (p, \phi_1) = p(1).$$

We are looking for all $p(x) = a_0 + a_1x + a_2x^2 + a_3x^3$ such that

$$0 = (p, \phi_0) = a_0, \quad 0 = (p, \phi_1) = a_0 + a_1 + a_2 + a_3.$$

This is clearly the same as $\text{span}[-x + x^2, -x + x^3]$.

5. (20 points) Consider the operator $T : \mathbb{R}_1[x] \rightarrow \mathbb{R}_2[x]$ given by $Tp(x) = (1+x)p(x)$. Let $\mathbf{e} = \{1, x\}$ and $\mathbf{f} = \{1, x, x^2\}$ be the respective canonical bases for $\mathbb{R}_1[x]$ and $\mathbb{R}_2[x]$, and let \mathbf{e}^* and \mathbf{f}^* be the corresponding dual bases for $\mathbb{R}_1[x]^*$ and $\mathbb{R}_2[x]^*$. What is the matrix for T^* written in the bases \mathbf{f}^* and \mathbf{e}^* ?

Note that

$$T1 = 1 + x, \quad Tx = x + x^2.$$

The matrix representation for T w.r.t. \mathbf{e} and \mathbf{f} is

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix}.$$

Therefore, the matrix representation for T^* w.r.t. \mathbf{f}^* and \mathbf{e}^* is A^{Tr} .

6. (20 points) If $T = R^{-1}SR$, where $R \in \mathbf{GL}(\mathcal{V})$, prove that $P(T) = R^{-1}P(S)R$ for every polynomial $P \in \mathbb{F}[x]$. Conclude that the minimal polynomials for T and S are the same.

Note that $T^k = R^{-1}S^kR$ for all $k \geq 0$. (This is easy to prove by induction.) Then if $P(x) = \sum_j a_j x^j$

$$P(T) = \sum_j a_j T^j = \sum_j a_j R^{-1}S^j R = R^{-1} \left(\sum_j a_j S^j \right) R = R^{-1}P(S)R,$$

where we have used elementary properties of matrix multiplication. Therefore $P(T) = 0$ if and only if $R^{-1}P(S)R = 0$, and since R is invertible, if and only if $P(S) = 0$. Using the definition of $\min P$ it follows that the minimal polynomial for both operators is the same.

7. (20 points) Let $S \in \mathcal{L}(\mathcal{V})$. Then

$$\ker S^k \subseteq \ker S^{k+1} \quad \forall k.$$

Why?

If $S^k v = 0$, then $S^{k+1} v = S S^k v = 0$.

Assume now that

$$\ker S^k = \ker S^{k+1},$$

pick $u \in \mathcal{V}$ such that $S^{k+2}u = 0$, and define $v = Su$. Then $v \in \ker S^{k+1}$. Why?

$$S^{k+1}v = S^{k+2}u = 0.$$

This implies that $S^{k+1}u = 0$. Why?

We have shown that $v \in \ker S^{k+1} = \ker S^k$, and therefore $S^k v = 0$, which implies that $S^{k+1}u = S^k v = 0$.

We have thus proved that if $\ker S^k = \ker S^{k+1}$, then $\ker S^{k+1} = \ker S^{k+2}$. Explain how.

The previous argument shows that $\ker S^{k+2} \subseteq \ker S^{k+1}$ for this particular value of k . However, $\ker S^{k+1} \subseteq \ker S^{k+2}$, and this proves that both sets are equal.

8. (20 points) Let A be a square matrix such that $A \neq 0$ and $A \neq I$. Assume that

$$A^2 - A = 0.$$

Show that

$$\chi_A(x) = (-1)^n x^k (x - 1)^{n-k}, \quad 1 \leq k \leq n - 1.$$

The polynomial $P(\lambda) = \lambda^2 - \lambda$ satisfies $P(A) = 0$ and neither of its divisors satisfies this property. Therefore $\min P_A(\lambda) = \lambda(\lambda - 1)$. The characteristic polynomial is a multiple of this polynomial containing no other irreducible factors (roots). Therefore it has the given form.

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Second midterm exam Part 1/2

Partial solutions

1. (15 points) Let $\{v_1^*, \dots, v_n^*\}$ be a basis for \mathcal{V}^* , where \mathcal{V} is a vector space over \mathbb{F} . Consider the alternating bilinear forms

$$(v_i^* \wedge v_j^*)(u_1, u_2) = (u_1, v_i^*)(u_2, v_j^*) - (u_1, v_j^*)(u_2, v_i^*), \quad i < j.$$

Show that they are a basis for the space of alternating bilinear forms in \mathcal{V} .

Let $\{v_1, \dots, v_n\}$ be the basis of \mathcal{V} such that

$$(v_i, v_j) = \delta_{ij}. \tag{1}$$

We first show linear independence of the given bilinear forms. If $\sum_{i < j} a_{ij}(v_i^* \wedge v_j^*) = 0$, then for $l < m$

$$\begin{aligned} 0 &= \sum_{i < j} a_{ij}(v_i^* \wedge v_j^*)(v_l, v_m) \\ &= \sum_{i < j} a_{ij}((v_l, v_i^*)(v_m, v_j^*) - (v_l, v_j^*)(v_m, v_i^*)) \\ &= \sum_{i < j} a_{ij}(\delta_{l,i}\delta_{m,j} - \delta_{l,j}\delta_{m,i}) && \text{(by (1))} \\ &= a_{lm}. && (i < j, l < m \text{ so } i = m, j = l \text{ not possible}) \end{aligned}$$

This proves that the set is linearly independent. To prove that it is spanning, we take ψ bilinear and alternating, define $a_{ij} = \psi(v_i, v_j)$ for $i < j$ and

$$\varphi = \sum_{i < j} a_{ij}(v_i^* \wedge v_j^*).$$

With the same argument above, we verify that $\varphi(v_i, v_j) = a_{ij} = \psi(v_i, v_j)$ for all $i < j$. However, both bilinear forms are alternating, so this proves that $\varphi(v_i, v_j) = \psi(v_i, v_j)$ for all i, j .

Alternatively, we can count the number of elements $v_i^* \wedge v_j^*$ and notice that it coincides with the dimension of the subspace of alternating bilinear forms, which is $\frac{1}{2}n(n-1)$.

2. (15 points) Let $S, T \in \mathcal{L}(\mathcal{V})$ be such that $ST = TS$, where \mathcal{V} is a vector space over \mathbb{C} . Assume that $0 \neq v \in \mathcal{V}$ satisfies $Tv = \lambda v$ for some $\lambda \in \mathbb{C}$.

- (a) Show that $\mathcal{W} = \ker(T - \lambda I)$ is S -invariant and has dimension at least one.

By hypothesis $0 \neq v \in \mathcal{W}$, so \mathcal{W} is at least one dimensional. If $w \in \mathcal{W}$, then

$$\begin{aligned} (T - \lambda I)Sw &= S(T - \lambda I)w && (S \text{ and } T \text{ commute}) \\ &= S0 = 0 && (w \in \mathcal{W}) \end{aligned}$$

which proves that \mathcal{W} is S -invariant.

- (b) Consider the operator $S_{\mathcal{W}} \in \mathcal{L}(\mathcal{W})$ given by $S_{\mathcal{W}}w = Sw$ for $w \in \mathcal{W}$. Show that it has at least one eigenvector.

$S_{\mathcal{W}}$ is a linear operator in a vector space of dimension at least one over \mathbb{C} . Therefore its characteristic polynomial has at least one root μ , and there exists $0 \neq w \in \mathcal{W}$ such that $S_{\mathcal{W}}w = Sw = \mu w$.

- (c) Conclude from the previous argument that two commuting operators in a \mathbb{C} -vector space have at least one common eigenvector.

The vector in (b) is an eigenvector for S , and for T , since it is an element of $\mathcal{W} = \ker(T - \lambda I)$.

- (d) Find an example of the above where the eigenvalue is different.

Take $T = I$ and $S = 0$ in any \mathcal{V} . All vectors are eigenvectors and the eigenvalue is 1 for T and 0 for S .

3. (15 points) Let $T \in \mathcal{L}(\mathcal{M}(n, \mathbb{R}))$ be given by $TA = A + A^{Tr}$.

- (a) Compute the characteristic polynomial of T . (Hint. Use a basis of $\mathcal{M}(n, \mathbb{F})$ using exclusively symmetric and skew-symmetric matrices.)

Let

$$\begin{aligned}\mathcal{V}_1 &= \{A \in \mathcal{M}(n, \mathbb{F}) : A^{Tr} = A\}, \\ \mathcal{V}_2 &= \{A \in \mathcal{M}(n, \mathbb{F}) : A^{Tr} = -A\}.\end{aligned}$$

It is simple to see that $\mathcal{V}_1 \oplus \mathcal{V}_2 = \mathcal{M}(n, \mathbb{F})$ and $\dim \mathcal{V}_1 = \frac{1}{2}n(n+1) = k$, while $\dim \mathcal{V}_2 = \frac{1}{2}n(n-1)$. Consider a basis of the space in the form

$$\{\underbrace{A_1, \dots, A_k}_{\text{basis for } \mathcal{V}_1}, \underbrace{A_{k+1}, \dots, A_{n^2}}_{\text{basis for } \mathcal{V}_2}\}.$$

Since $TA = 2A$ for $A \in \mathcal{V}_1$ and $TA = 0$ for $A \in \mathcal{V}_2$, the matrix representing T in this basis is diagonal

$$\begin{bmatrix} 2I_k & 0 \\ 0 & 0 \end{bmatrix}$$

and the characteristic polynomial of T is the same as the one for the matrix, namely $(2 - \lambda)^k (-\lambda)^{n^2 - k}$ where $k = \frac{1}{2}n(n+1)$.

- (b) Find $\min P_{T,A}$ for an arbitrary A . (Hint. There are three cases: A symmetric, A skewsymmetric, and A neither symmetric nor skew-symmetric.)

If $0 \neq A \in \mathcal{V}_1$, then $(T - 2I)A = 0$ so $\min P_{T,A}(\lambda) = \lambda - 2$. Similarly for $0 \neq A \in \mathcal{V}_2$, $\min P_{T,A} = \lambda$. Finally, for a general A ,

$$TA = A + A^{Tr}, \quad T^2A = 2(A + A^{Tr}),$$

so $(T^2 - 2T)A = 0$. If $A \notin \mathcal{V}_1$ and $A \notin \mathcal{V}_2$, then its minimal polynomial needs to be $\lambda^2 - 2\lambda = \lambda(\lambda - 2)$, since none of its divisors cancels A .

- (c) Find $\min P_T$.

The least common multiple of $\lambda - 2$, λ and $\lambda(\lambda - 2)$ is $\min P_T = \lambda(\lambda - 2)$.

- (d) Show that T is diagonalizable.

This follows from the argument in (a)

4. (15 points) Let $\Psi : \mathcal{V} \times \mathcal{V} \rightarrow \mathcal{V}$ be a bilinear map and let $v^* \in \mathcal{V}^*$.

- (a) Show that $\psi(v_1, v_2) = (\Psi(v_1, v_2), v^*)$ defines a bilinear form.
 For general $v_1, v_2, v_3 \in \mathcal{V}$ and $a, b \in \mathbb{F}$,

$$\begin{aligned} \psi(av_1 + bv_2, v_3) &= (\Psi(av_1 + bv_2, v_3), v^*) \\ &= (a\Psi(v_1, v_3) + b\Psi(v_2, v_3), v^*) && (\Psi \text{ is bilinear}) \\ &= a(\Psi(v_1, v_3), v^*) + b(\Psi(v_2, v_3), v^*) && (v^* \text{ is linear}) \\ &= a\psi(v_1, v_3) + b\psi(v_2, v_3). \end{aligned}$$

For identical reasons

$$\begin{aligned} \psi(v_3, av_1 + bv_2) &= (\Psi(v_3, av_1 + bv_2), v^*) \\ &= (a\Psi(v_3, v_1) + b\Psi(v_3, v_2), v^*) && (\Psi \text{ is bilinear}) \\ &= a(\Psi(v_3, v_1), v^*) + b(\Psi(v_3, v_2), v^*) && (v^* \text{ is linear}) \\ &= a\psi(v_3, v_1) + b\psi(v_3, v_2), \end{aligned}$$

for all $v_1, v_2, v_3 \in \mathcal{V}$ and $a, b \in \mathbb{F}$. This proves that ψ is bilinear.

- (b) Apply this to show that $\psi(A, B) = \text{trace}(B^{Tr} A)$ is a bilinear form in $\mathcal{M}(n, \mathbb{R})$.
 It is easy to prove that the map $\text{trace}(A) = a_{11} + \dots + a_{nn}$ is a linear form in $\mathcal{M}(n, \mathbb{R})$. We next prove that $\Psi(A, B) = B^{Tr} A$ is bilinear. This follows from very simple properties of the product of matrices and by the linearity of the transposition operator: for all $A, B, C \in \mathcal{M}(n, \mathbb{R})$ and $a, b \in \mathbb{R}$

$$\begin{aligned} \Psi(aA + bB, C) &= C^{Tr}(aA + bB) = aC^{Tr}A + bC^{Tr}B = a\Psi(A, C) + b\Psi(B, C), \\ \Psi(C, aA + bB) &= (aA + bB)^{Tr}C = aA^{Tr}C + bB^{Tr}C = a\Psi(C, A) + b\Psi(C, B). \end{aligned}$$

Bilinearity of ψ follows from (a).

- (c) Show that ψ is symmetric.
 This is a simple argument:

$$\begin{aligned} \psi(B, A) &= \text{trace}(A^{Tr} B) = \text{trace}((A^{Tr} B)^{Tr}) && (\text{since } \text{trace } C = \text{trace } C^{Tr}) \\ &= \text{trace}(B^{Tr} A) = \psi(A, B) && ((CD)^{Tr} = D^{Tr} C^{Tr}) \end{aligned}$$

5. (15 points) Let $T \in \mathcal{L}(\mathcal{V})$ be represented by the matrix

$$A = \begin{bmatrix} c & 1 & & \\ & c & 1 & \\ & & c & 1 \\ & & & c \end{bmatrix}.$$

(The numbers that are not displayed are zeros.) Show that it can also be represented by the matrix

$$B = \begin{bmatrix} c & & & \\ 1 & c & & \\ & 1 & c & \\ & & 1 & c \end{bmatrix}.$$

In other words, show that A and B are similar.

If $\{v_1, v_2, v_3, v_4\}$ is the basis with respect to which the matrix representation is A , then

$$Tv_1 = cv_1, \quad Tv_2 = cv_2 + v_1, \quad Tv_3 = cv_3 + v_2, \quad Tv_4 = cv_4 + v_3.$$

Let us then reorder the basis to get $\{v_4, v_3, v_2, v_1\}$ or, equivalently $w_j = v_{5-j}$ for $j = 1, \dots, 4$. Then

$$Tw_1 = cw_1 + w_2, \quad Tw_2 = cw_2 + w_3, \quad Tw_3 = cw_3 + w_4, \quad Tw_4 = cw_4.$$

The matrix representation w.r.t. this basis is therefore B .

6. (15 points) An operator $T \in \mathcal{L}(\mathcal{V})$ is cyclic if there exists a basis $\{v_1, v_2, \dots, v_n\}$ such that the associated matrix is

$$\begin{bmatrix} 0 & 0 & \dots & \dots & 0 & -a_0 \\ 1 & 0 & \dots & \dots & 0 & -a_1 \\ 0 & 1 & 0 & \dots & 0 & -a_2 \\ \vdots & \vdots & & \ddots & & \vdots \\ 0 & 0 & \dots & 1 & 0 & -a_{n-2} \\ 0 & 0 & \dots & 0 & 1 & -a_{n-1} \end{bmatrix}.$$

In this case, the vector $v = v_1$ is called cyclic as well. Show that $\min P_{T,v} = (-1)^n \chi_T$. (Hint. Write what having this matrix representation means in terms of the vectors of the basis.) Use this to prove that T is cyclic if and only if $\chi_T = (-1)^n \min P_T$.

The characteristic polynomial of this matrix/operator is $P(x) = (-1)^n(x^n + \sum_j a_j x^j)$. It is simple to see from the matrix representation that

$$T^j v = v_{j+1} \quad j = 0, \dots, n-1,$$

so $\{v, Tv, \dots, T^{n-1}v\} = \{v_1, \dots, v_n\}$ are linearly independent. This proves that the degree of the minimal polynomial for v is n , and since it has to be monic and divide the characteristic polynomial it follows that $\min P_{T,v}(x) = x^n + \sum_j a_j x^j$.

If T is cyclic, then we have seen that there exists v such that $\min P_{T,v} = (-1)^n \chi_T$. Since $\min P_T$ is monic, divides χ_T and is a multiple of $\min P_{T,v}$ it follows that $\min P_T = \min P_{T,v}$.

Assume that $\chi_T = (-1)^n \min P_T$. We will see next that there exists v such that $\min P_{T,v} = \min P_T$ (this is true for any operator). If we consider the vectors $v_1 = v, v_2 = Tv, \dots, v_n = T^{n-1}v$, it is clear that they are linearly independent (the degree of $\min P_{T,v}$ is n), so they form a basis for \mathcal{V} . Since $Tv_j = v_{j+1}$ for $j = 1, \dots, n-1$, the matrix representation of T w.r.t. this basis has the given form.

Side problem: there exists v such that $\min P_{T,v} = \min P_T$. Let

$$\min P_T = \Phi_1^{m_1} \dots \Phi_k^{m_k},$$

where Φ_j are relatively prime and irreducible (they cannot be factored). For each j , there exists v_j such that $\min P_{T,v_j} = \Phi_j^{m_j} Q_j$ for some polynomial Q_j . Otherwise, the factor $\Phi_j^{m_j}$ would not be in the minimal polynomial. Define then $w_j = Q_j(T)v_j$. It is very simple to see that $\min P_{T,w_j} = \Phi_j^{m_j}$. Finally, it is relatively easy to prove that $v = w_1 + \dots + w_k$ has $\min P_T$ as its minimal polynomial.